

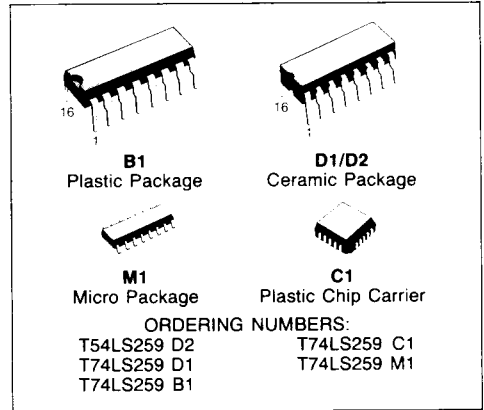
# T54LS259 T74LS259



## 8-BIT ADDRESSABLE LATCH

### DESCRIPTION

The T54LS259/T74LS259 is a high speed 8-bit Addressable Latch designed for general purpose storage applications in digital systems. It is a multifunctional device capable of storing single line data in eight addressable latches, and also a 1-of-8 decoder and demultiplexer with active HIGH outputs. The device also incorporates an active LOW common Clear for resetting all latches, as well as, an active LOW Enables.



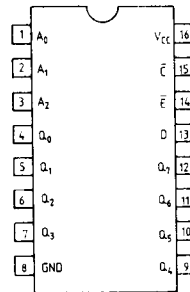
- SERIAL-TO-PARALLEL CONVERSION
- EIGHT BITS OF STORAGE WITH OUTPUT OF EACH BIT AVAILABLE
- RANDOM (ADDRESSABLE) DATA ENTRY
- ACTIVE HIGH DEMULTIPLEXING OR DECODING CAPABILITY
- EASILY EXPANDABLE
- COMMON CLEAR
- FULLY TTL AND CMOS COMPATIBLE

### PIN NAMES

A <sub>0</sub> , A <sub>1</sub> , A <sub>2</sub>	Address Inputs
D	Data Input
$\bar{E}$	Enable (Active LOW) Input
$\bar{C}$	Clear (Active LOW) Input
Q <sub>0</sub> to Q <sub>7</sub>	Parallel Latch Outputs

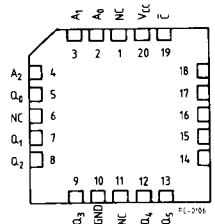
### PIN CONNECTION (top view)

#### DUAL IN LINE



PC-0144

#### CHIP CARRIER



PC-206

NC = No Internal Connection

**TRUTH TABLE - PRESENT OUTPUT STATES**

**MODE SELECTION**

$\bar{C}$	$\bar{E}$	D	A <sub>0</sub>	A <sub>1</sub>	A <sub>2</sub>	Q <sub>0</sub>	Q <sub>1</sub>	Q <sub>2</sub>	Q <sub>3</sub>	Q <sub>4</sub>	Q <sub>5</sub>	Q <sub>6</sub>	Q <sub>7</sub>	MODE	
L	H	X	X	X	X	L	L	L	L	L	L	L	L	Clear Demultiplex	
L	L	L	L	L	L	L	L	L	L	L	L	L	L		
L	L	H	L	L	L	H	L	L	L	L	L	L	L		
L	L	L	H	L	L	L	L	L	L	L	L	L	L		
L	L	H	H	L	L	L	H	L	L	L	L	L	L		
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮		
L	L	H	H	H	H	L	L	L	L	L	L	L	H		
H	H	X	X	X	X	Q <sub>n-1</sub> →							Memory		
H	L	L	L	L	L	L	Q <sub>n-1</sub>	Q <sub>n-1</sub>	Q <sub>n-1</sub>	Q <sub>n-1</sub> →					Addressable Latch
H	L	H	L	L	L	H	Q <sub>n-1</sub>	Q <sub>n-1</sub>	Q <sub>n-1</sub>	Q <sub>n-1</sub> →					
H	L	L	H	L	L	Q <sub>n-1</sub>	L	Q <sub>n-1</sub>	Q <sub>n-1</sub> →						
H	L	H	H	L	L	Q <sub>n-1</sub>	H	Q <sub>n-1</sub>	Q <sub>n-1</sub> →						
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮		
H	L	L	H	H	H	Q <sub>n-1</sub> →					Q <sub>n-1</sub>	L			
H	L	H	H	H	H	Q <sub>n-1</sub> →					Q <sub>n-1</sub>	H			

$\bar{E}$	$\bar{C}$	MODE
L	H	Addressable Latch
H	H	Memory
L	L	Active HIGH Eight-Channel Demultiplexer
H	L	Clear

X = Don't Care  
 L = LOW Voltage Level  
 H = HIGH Voltage Level  
 Q<sub>n-1</sub> = Previous Output State

**ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	Value	Unit
V <sub>CC</sub>	Supply Voltage	-0.5 to 7	V
V <sub>I</sub>	Input Voltage, Applied to Input	-0.5 to 15	V
V <sub>O</sub>	Output Voltage, Applied to Output	-0.5 to 10	V
I <sub>I</sub>	Input Current, Into Inputs	-30 to 5	mA
I <sub>O</sub>	Output Current, Into Outputs	30	mA

Stresses in excess of those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions in excess of those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

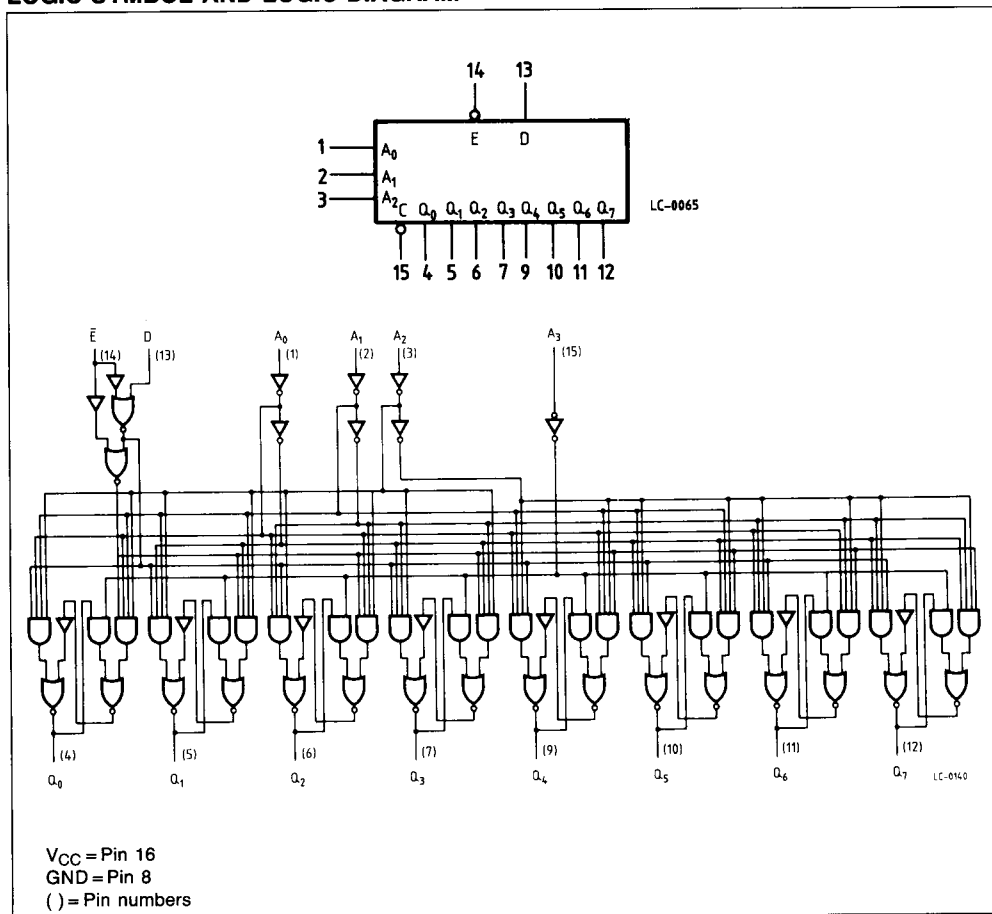
**GUARANTEED OPERATING RANGES**

Part Numbers	Supply Voltage			Temperature
	Min	Typ	Max	
T54LS259D2	4.5 V	5.0 V	5.5 V	-55°C to +125°C
T74LS259XX	4.75 V	5.0 V	5.25 V	0°C to +70°C

XX = package type.



## LOGIC SYMBOL AND LOGIC DIAGRAM

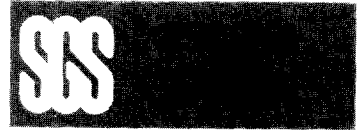


### FUNCTIONAL DESCRIPTION

The LS259 has four modes of operation as shown in the mode selection table. In the addressable latch mode, data on the Data line (D) is written into the addressed latch. The address latch will follow three data input with all non-addressed latches remaining in their previous states. In the memory mode, all latches remain in their previous state and are unaffected by the Data or Address input. In one-of-eight decoding or demultiplexing mode, the addressed output will follow the state of the D

input with all other inputs in the LOW state. In the clear mode all outputs are LOW and unaffected by the address and data inputs.

When operating the LS259 as an addressable latch, changing more than one bit of the address could impose a transient wrong address. Therefore, this should only be done while in the memory mode. The truth table below summarizes the operations of the LS259.



### DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE

Symbol	Parameter		Limits			Test Conditions (Note 1)		Units
			Min.	Typ.	Max.			
V <sub>IH</sub>	Input HIGH Voltage		2.0			Guaranteed input Logical HIGH Voltage for all Inputs		V
V <sub>IL</sub>	Input LOW Voltage	54			0.7	Guaranteed input Logical LOW Voltage for all Inputs		V
		74			0.8			
V <sub>CD</sub>	Input Clamp Diode Voltage				-1.5	V <sub>CC</sub> = MIN, I <sub>IN</sub> = -18mA		V
V <sub>OH</sub>	Output HIGH Voltage	54	2.4	3.4		V <sub>CC</sub> = MIN, I <sub>OH</sub> = -400μA, V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub> per Truth Table		V
		74	2.4	3.1				
V <sub>OL</sub>	Output LOW Voltage	54,74		0.25	0.4	I <sub>OL</sub> = 4.0mA	V <sub>CC</sub> = MIN, V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub> per Truth Table	V
		74		0.35	0.5	I <sub>OL</sub> = 8.0mA		
I <sub>IH</sub>	Input HIGH Current A <sub>0</sub> , A <sub>1</sub> , A <sub>2</sub> , D, $\bar{C}$ E				20 40	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 2.7V		μA
	Input HIGH Current A <sub>0</sub> , A <sub>1</sub> , A <sub>2</sub> , D, $\bar{C}$ E				0.1 0.2	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 7.0V		mA
I <sub>IL</sub>	Input LOW Current A <sub>0</sub> , A <sub>1</sub> , A <sub>2</sub> , D, $\bar{C}$ E				-0.4 -0.8	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 0.4V		mA
I <sub>OS</sub>	Output Short Circuit Current (Note 2)		-20		-100	V <sub>CC</sub> = MAX, V <sub>OUT</sub> = 0V		mA
I <sub>CC</sub>	Power Supply Current			20	36	V <sub>CC</sub> = MAX		mA

### AC CHARACTERISTICS: T<sub>A</sub> = 25°C

Symbol	Parameter		Limits			Test Conditions		Units
			Min.	Typ.	Max.			
t <sub>PLH</sub>	Turn-Off Delay, Enab. to Out.			22	35	Fig. 1	V <sub>CC</sub> = 5.0V C <sub>L</sub> = 15pF	ns
t <sub>PHL</sub>	Turn-On Delay, Enab. to Out.			15	24			
t <sub>PLH</sub>	Turn-Off Delay, Data to Output			20	32	Fig. 2		ns
t <sub>PHL</sub>	Turn-On Delay, Data to Output			13	21			
t <sub>PLH</sub>	Turn-Off Delay, Addr. to Out.			24	38	Fig. 3		ns
t <sub>PHL</sub>	Turn-On Delay, Addr. to Out.			18	29			
t <sub>PHL</sub>	Turn-On Delay, Clear to Output			17	27	Fig. 5	ns	

#### Notes:

- 1) Conditions for testing, not shown in the Table, are chosen to guarantee operation under "worst case" conditions.
- 2) Not more than one output should be shorted at a time.
- 3) Typical values are at V<sub>CC</sub> = 5.0V, T<sub>A</sub> = 25°C



T5ALS259

T7ALS259

**AC SET-UP REQUIREMENTS:**  $T_A = 25^\circ\text{C}$

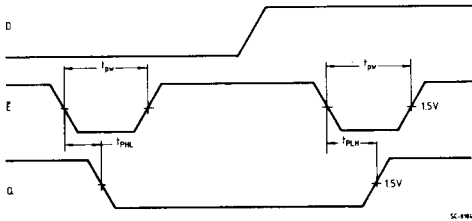
Symbol	Parameter	Limits			Test Conditions	Units
		Min.	Typ.	Max.		
$t_{sH}$	Set-up Time HIGH, Data to Enable	20	13		Fig. 4 $V_{CC} = 5.0\text{V}$	ns
$t_{hH}$	Hold Time HIGH, Data to Enable	0	-7.0			ns
$t_{sL}$	Set-up Time LOW, Data to Enable	15	7.0			ns
$t_{hL}$	Hold Time LOW, Data to Enable	0	10			ns
$t_{sA-\bar{E}}$	Set-up Time, Address to Enable (Note 4)	0	-7.0		Fig. 6	ns
$t_{pW\bar{E}}$	Enable Pulse Width	17	12		Fig. 1	ns

**Notes:**

- 4) The address to Enable Set-up Time is the time before the HIGH to LOW Enable transition that the Address must be stable so that the correct latch is addressed and the other latches are not affected.
- 5) The shaded areas indicate when the inputs are permitted to change for predictable output performance.

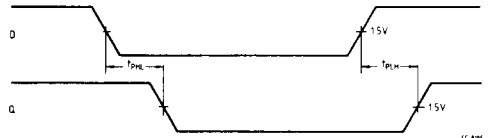
**AC WAVEFORMS**

Fig. 1 Turn-On and Turn-Off Delays, Enable to Output and Enable Pulse Width



OTHER CONDITIONS:  $\bar{C} = H, A = \text{STABLE}$

Fig. 2 Turn-On and Turn-Off Delays, Data to Output

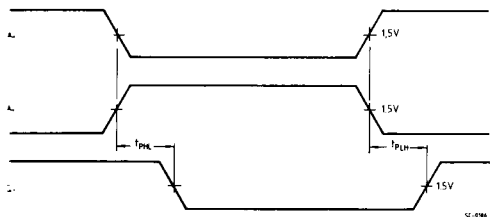


OTHER CONDITIONS:  $\bar{E} = L, \bar{C} = H, A = \text{STABLE}$



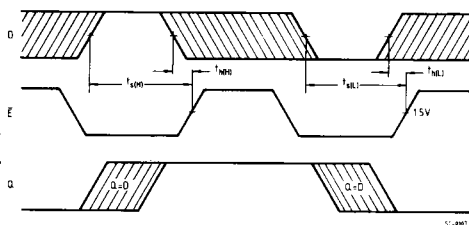
AC WAVEFORMS (continued)

Fig. 3 Turn-On and Turn-Off Delays, Address to Output



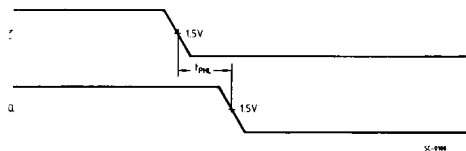
OTHER CONDITIONS:  $\bar{E} = L, \bar{C} = L, D = H$

Fig. 4 Set-up and Hold Time, Data to Enable



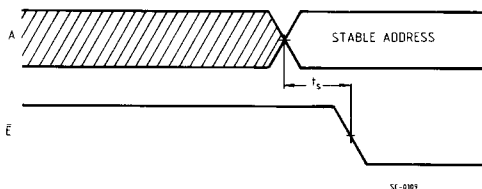
OTHER CONDITIONS:  $\bar{C} = H, A = \text{STABLE}$

Fig. 5 Turn-On Delay, Clear to Output



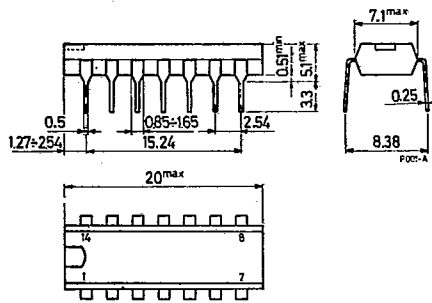
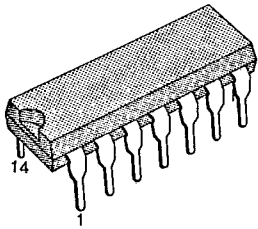
OTHER CONDITIONS:  $\bar{E} = H$

Fig. 6 Set-up Time, Address to Enable

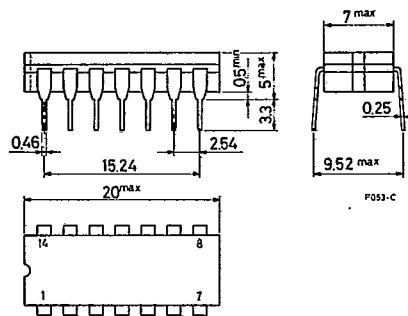
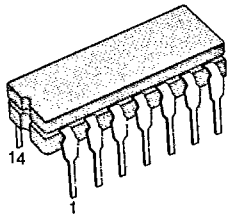


OTHER CONDITIONS:  $\bar{C} = H$

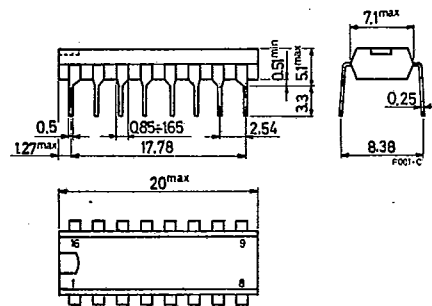
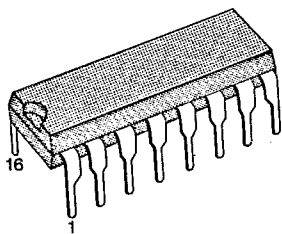
### 14-LEAD PLASTIC DIP



### 14-LEAD CERAMIC DIP



### 16-LEAD PLASTIC DIP



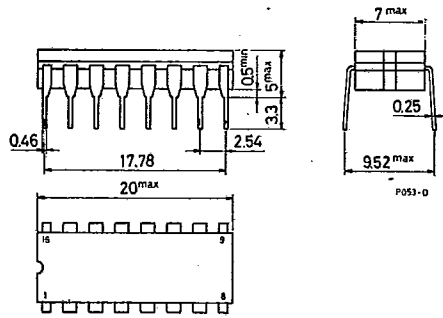
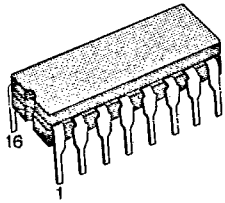
# Packages

67C 16545

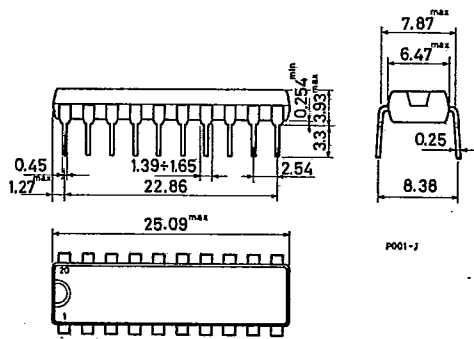
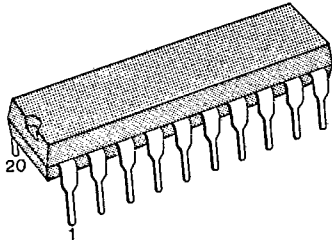
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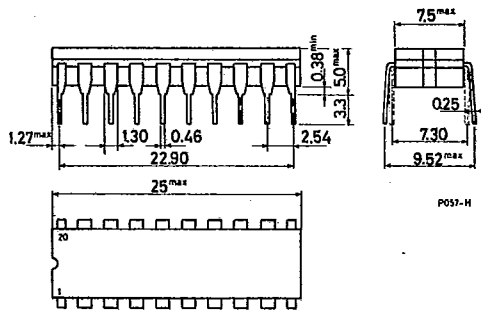
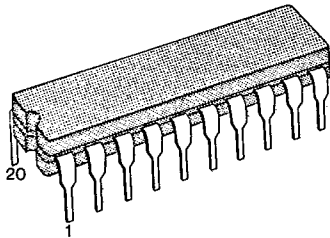
## 16-LEAD CERAMIC DIP



## 20-LEAD PLASTIC DIP

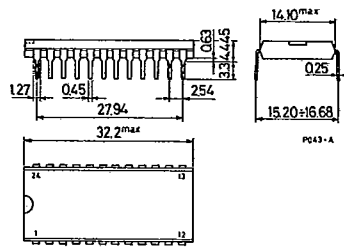
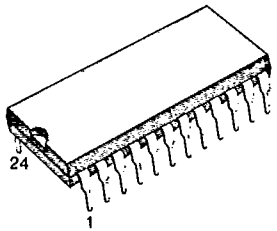


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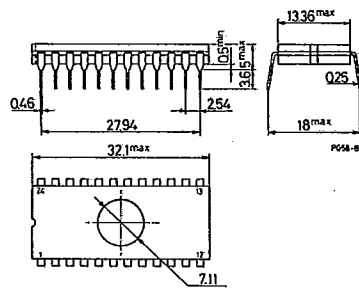
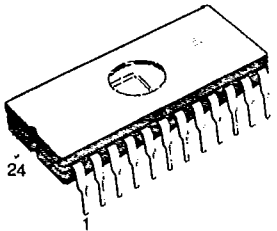




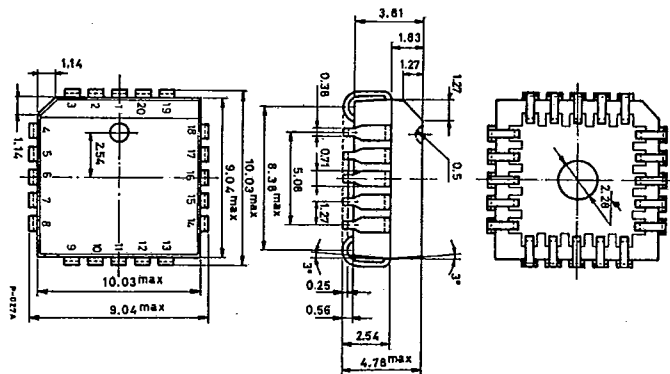
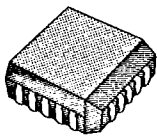
24-LEAD PLASTIC DIP



24-LEAD CERAMIC DIP



CHIP CARRIER 20 LEAD PLASTIC



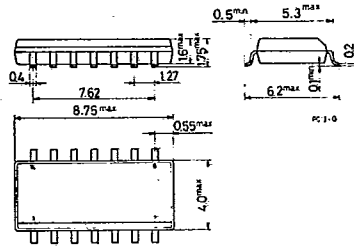
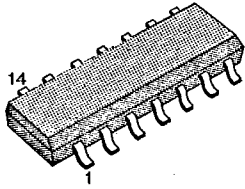
# Packages

67C 16547

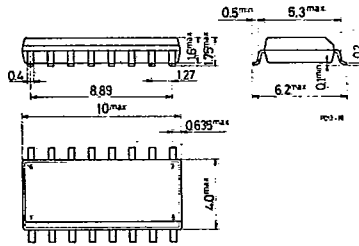
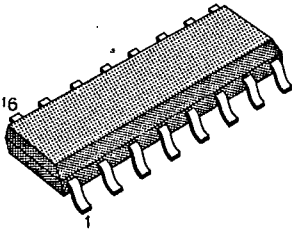
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## 14-LEAD PLASTIC DIP MICROPACKAGE



## 16-LEAD PLASTIC DIP MICROPACKAGE



NOTE: FOR 20-LEAD PLASTIC DIP MICROPACKAGE CONTACT SGS

# Surface Mounted

67C 16548

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T-90-20

One possible solution to the important problem of PWB minimization, is that of using surface mounted components. Integrated circuits in SO (Small Outline) packages are made up of standard chips mounted in very small plastic packages. The advantages given by using these devices are:

### PWB Reduction

This is by far the most important advantage since the reduction of PWB size varies from 40 to 60% in comparison with standard board types. (See page 584 for package dimensions.)

### Assembly Cost Reduction

SO Devices require no preliminary operation prior to mounting and can therefore be easily utilized in fully automatic equipment.

### Increasing Reliability

The following characteristics lead to a higher level of reliability with respect to their standard packaged counter parts:

- The mounting system is fully automatic
- PWB number and the interconnections between them are reduced when the same number of devices are used.
- The high density of components on the board makes it thermally much more stable.

### Noise Reduction and Improved Frequency Response

The reduction of the length of the connecting wires between the leads and the silicon guarantees a more homogeneous propagation delay between the external pins, with respect to the standard type.

### Assembly Without Board Holes

The devices are placed on the board and soldered. This technology permits a higher level of tolerance in the positioning (automatic) of the device. For the standard DIP types this must be done with great accuracy due to the insertion of the leads into their holes.

