

Features

- Fast read access time – 45ns
- Low-power CMOS operation
 - 100µA max standby
 - 30mA max active at 5MHz
- JEDEC standard packages
 - 40-lead PDIP
 - 44-lead PLCC
- Direct upgrade from 512K (Atmel® AT27C516) EPROM
- 5V ± 10% power supply
- High-reliability CMOS technology
 - 2000V ESD protection
 - 200mA latchup immunity
- Rapid programming algorithm – 100µs/word (typical)
- CMOS- and TTL-compatible inputs and outputs
- Integrated product identification code
- Industrial and automotive temperature ranges
- Green (Pb/halide-free) packaging option

1. Description

The Atmel AT27C1024 is a low-power, high-performance 1,048,576-bit, one-time programmable, read-only memory (OTP EPROM) organized as 64K by 16 bits. It requires only one 5V power supply in normal read mode operation. Any word can be accessed in less than 45ns, eliminating the need for speed reducing WAIT states. The x16 organization makes this part ideal for high-performance, 16- and 32-bit microprocessor systems.

In read mode, the AT27C1024 typically consumes 15mA. Standby mode supply current is typically less than 10µA.

The AT27C1024 is available in industry-standard, JEDEC-approved, one-time programmable (OTP) PDIP and PLCC packages. The device features two-line control (\overline{CE} , \overline{OE}) to eliminate bus contention in high-speed systems.

With high-density, 64K word storage capability, the AT27C1024 allows firmware to be stored reliably and to be accessed by the system without the delays of mass storage media.

The AT27C1024 has additional features to ensure high quality and efficient production use. The rapid programming algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 100µs/word. The integrated product identification code electronically identifies the device and manufacturer. This feature is used by industry standard programming equipment to select the proper programming algorithms and voltages.



1Mb (64K x 16)
One-time
Programmable
Read-only Memory

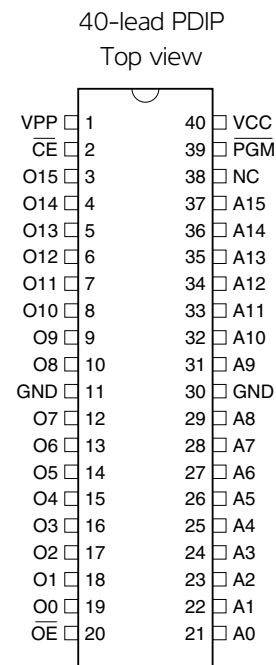
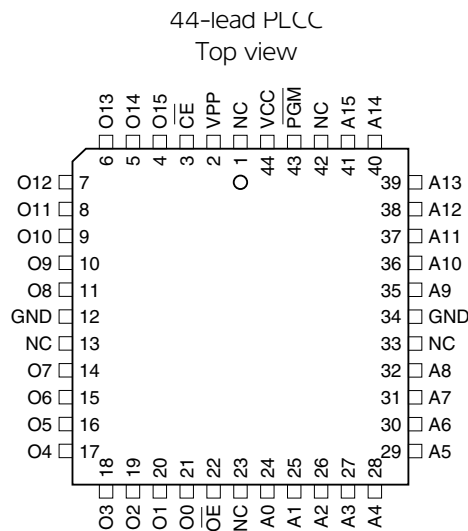
Atmel AT27C1024



2. Pin configurations

| Pin name | Function |
|------------------|----------------|
| A0 - A15 | Addresses |
| O0 - O15 | Outputs |
| \overline{CE} | Chip enable |
| \overline{OE} | Output enable |
| \overline{PGM} | Program strobe |
| NC | No connect |

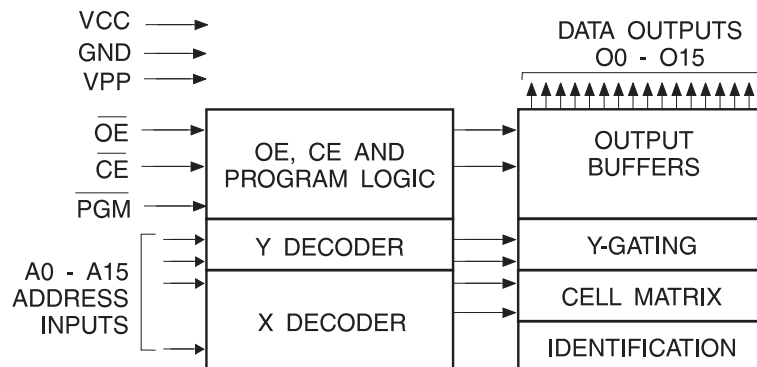
Note: Both GND pins must be connected.



3. System considerations

Switching between active and standby conditions via the chip enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device nonconformance. At a minimum, a 0.1 μ F, high-frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the V_{CC} and ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7 μ F bulk electrolytic capacitor should be utilized, again connected between the V_{CC} and ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

Figure 3-1. Block diagram



4. Absolute maximum ratings*

| | |
|--|---------------------------------|
| Temperature under bias | -55°C to + 125°C |
| Storage temperature | -65°C to + 150°C |
| Voltage on any pin with respect to ground | -2.0V to + 7.0V ⁽¹⁾ |
| Voltage on A9 with respect to ground | -2.0V to + 14.0V ⁽¹⁾ |
| V _{PP} supply voltage with respect to ground | -2.0V to + 14.0V ⁽¹⁾ |

*NOTICE: Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: 1. Minimum voltage is -0.6V DC, which may undershoot to -2.0V for pulses of less than 20ns. Maximum output pin voltage is V_{CC} + 0.75V DC, which may overshoot to +7.0V for pulses of less than 20ns.

5. DC and AC characteristics

Table 5-1. Operating modes

| Mode/Pin | \overline{CE} | \overline{OE} | PGM | Ai | V _{PP} | Outputs |
|---------------------------------------|-----------------|-----------------|------------------|---|------------------|---------------------|
| Read | V _{IL} | V _{IL} | X ⁽¹⁾ | Ai | X | D _{OUT} |
| Output disable | X | V _{IH} | X | X | X | High Z |
| Standby | V _{IH} | X | X | X | X ⁽⁵⁾ | High Z |
| Rapid program ⁽²⁾ | V _{IL} | V _{IH} | V _{IL} | Ai | V _{PP} | D _{IN} |
| PGM verify | V _{IL} | V _{IL} | V _{IH} | Ai | V _{PP} | D _{OUT} |
| PGM inhibit | V _{IH} | X | X | X | V _{PP} | High Z |
| Product identification ⁽⁴⁾ | V _{IL} | V _{IL} | X | A9 = V _H ⁽³⁾ A0 = V _{IH} or V _{IL} A1 - A15 = V _{IL} | V _{CC} | Identification code |

- Notes:
1. X can be V_{IL} or V_{IH}.
 2. Refer to programming characteristics.
 3. V_H = 12.0 ± 0.5V.
 4. Two identifier words may be selected. All Ai inputs are held low (V_{IL}), except A9, which is set to V_H, and A0, which is toggled low (V_{IL}) to select the manufacturer's identification word and high (V_{IH}) to select the device code word.
 5. Standby V_{CC} current (I_{SB}) is specified with V_{PP} = V_{CC}. V_{CC} > V_{PP} will cause a slight increase in I_{SB}.

Table 5-2. DC and AC operating conditions for read operation

| | | Atmel AT27C1024 | |
|------------------------------|-------|-----------------|--------------|
| | | -45 | -70 |
| Operating temp. (case) | Ind. | -40°C - 85°C | -40°C - 85°C |
| | Auto. | | |
| V _{CC} power supply | | 5V ± 10% | 5V ± 10% |

Table 5-3. DC and operating characteristics for read operation

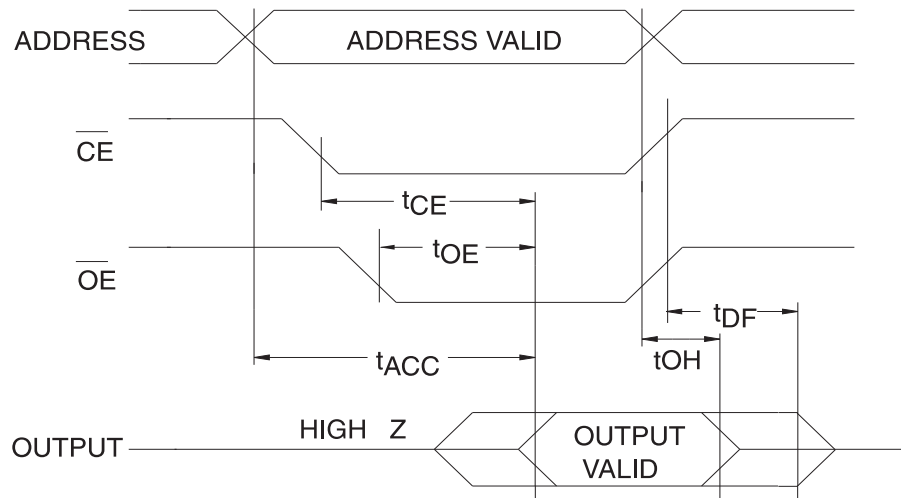
| Symbol | Parameter | Condition | Min | Max | Units |
|-----------------|-------------------------------------|---|-------|----------------|---------|
| I_{LI} | Input load current | $V_{IN} = 0V \text{ to } V_{CC}$ | Ind. | ± 1 | μA |
| | | | Auto. | ± 5 | μA |
| I_{LO} | Output leakage current | $V_{OUT} = 0V \text{ to } V_{CC}$ | Ind. | ± 5 | μA |
| | | | Auto. | ± 10 | μA |
| $I_{PP1}^{(2)}$ | $V_{PP}^{(1)}$ read/standby current | $V_{PP} = V_{CC}$ | | 10 | μA |
| I_{SB} | $V_{CC}^{(1)}$ standby current | $I_{SB1} \text{ (CMOS), } \overline{CE} = V_{CC} \pm 0.3V$ | | 100 | μA |
| | | $I_{SB2} \text{ (TTL), } \overline{CE} = 2.0 \text{ to } V_{CC} + 0.5V$ | | 1 | mA |
| I_{CC} | V_{CC} active current | $f = 5MHz, I_{OUT} = 0mA, \overline{CE} = V_{IL}$ | | 30 | mA |
| V_{IL} | Input low voltage | | -0.6 | 0.8 | V |
| V_{IH} | Input high voltage | | 2.0 | $V_{CC} + 0.5$ | V |
| V_{OL} | Output low voltage | $I_{OL} = 2.1mA$ | | 0.4 | V |
| V_{OH} | Output high voltage | $I_{OH} = -400\mu A$ | 2.4 | | V |

- Notes:
- V_{CC} must be applied simultaneously with or before V_{PP} , and removed simultaneously with or after V_{PP} .
 - V_{PP} may be connected directly to V_{CC} , except during programming. The supply current would then be the sum of I_{CC} and I_{PP} .

Table 5-4. AC characteristics for read operation

| Symbol | Parameter | Condition | Atmel AT27C1024 | | | | Units |
|---------------------------------|---|--|-----------------|-----|-----|-----|-------|
| | | | -45 | | -70 | | |
| | | | Min | Max | Min | Max | |
| t _{ACC} ⁽¹⁾ | Address to output delay | $\overline{CE} = \overline{OE} = V_{IL}$ | | 45 | | 70 | ns |
| t _{CE} ⁽¹⁾ | \overline{CE} to output delay | $\overline{OE} = V_{IL}$ | | 45 | | 70 | ns |
| t _{OE} ⁽¹⁾ | \overline{OE} to output delay | $\overline{CE} = V_{IL}$ | | 20 | | 25 | ns |
| t _{DF} ⁽¹⁾ | \overline{OE} or \overline{CE} high to output float, whichever occurred first | | | 20 | | 25 | ns |
| t _{OH} | Output hold from address, \overline{CE} or \overline{OE} , whichever occurred first | | 7 | | 7 | | ns |

- Note:
- See AC waveforms for read operation.

Figure 5-1. AC waveforms for read operation⁽¹⁾

- Notes:
1. Timing measurement reference level is 1.5V for -45. Input AC drive levels are $V_{IL} = 0.0V$ and $V_{IH} = 3.0V$. Timing measurement reference levels for all other speed grades are $V_{OL} = 0.8V$ and $V_{OH} = 2.0V$. Input AC drive levels are $V_{IL} = 0.45V$ and $V_{IH} = 2.4V$.
 2. \overline{OE} may be delayed up to $t_{CE} - t_{OE}$ after the falling edge of \overline{CE} without impact on t_{CE} .
 3. \overline{OE} may be delayed up to $t_{ACC} - t_{OE}$ after the address is valid without impact on t_{ACC} .
 4. This parameter is only sampled, and is not 100% tested.
 5. Output float is defined as the point when data is no longer driven.

Table 5-5. Pin capacitance

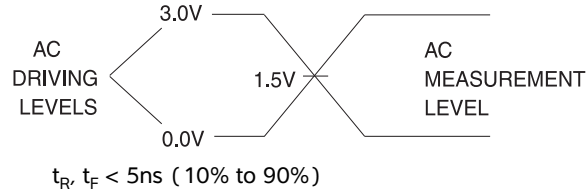
f = 1MHz, T = 25°C⁽¹⁾

| Symbol | Typ | Max | Units | Conditions |
|-----------|-----|-----|-------|----------------|
| C_{IN} | 4 | 10 | pF | $V_{IN} = 0V$ |
| C_{OUT} | 8 | 12 | pF | $V_{OUT} = 0V$ |

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled, and is not 100% tested.

Figure 5-2. Input test waveforms and measurement levels

For -45 devices only:



For -70 devices only:

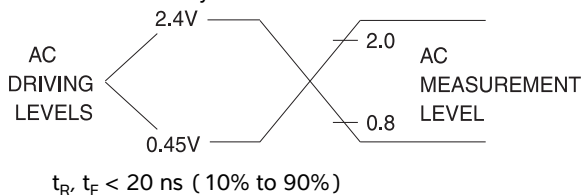
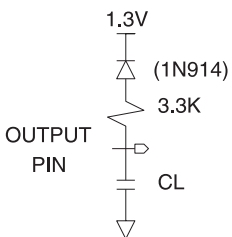
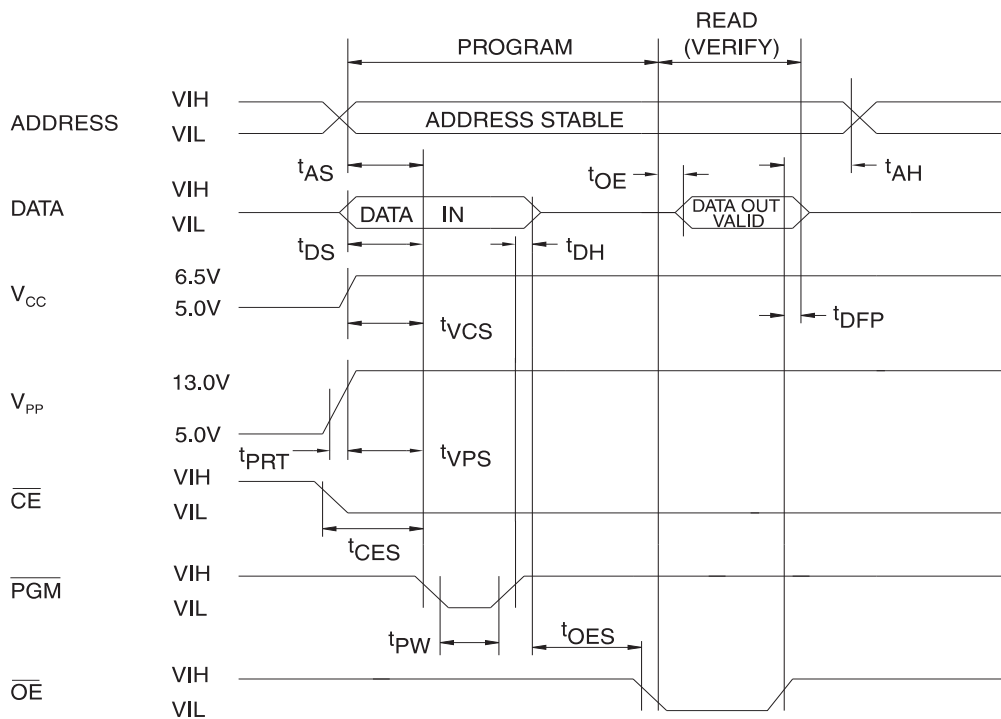


Figure 5-3. Output test load



Note: 1. $C_L = 100\text{pF}$ including jig capacitance, except -45 devices, where $C_L = 30\text{pF}$.

Figure 5-4. Programming waveforms⁽¹⁾



- Notes:
1. The input timing reference is 0.8V for V_{IL} and 2.0V for V_{IH} .
 2. t_{OE} and t_{DFP} are characteristics of the device, but must be accommodated by the programmer.
 3. When programming the Atmel AT27C1024, a 0.1 μF capacitor is required across V_{PP} and ground to suppress spurious voltage transients.

Table 5-6. DC programming characteristics

 $T_A = 25 \pm 5^\circ\text{C}$, $V_{CC} = 6.5 \pm 0.25\text{V}$, $V_{PP} = 13.0 \pm 0.25\text{V}$

| Symbol | Parameter | Test conditions | Limits | | Units |
|-----------|--|---|--------|----------------|---------------|
| | | | Min | Max | |
| I_{LI} | Input load current | $V_{IN} = V_{IL}, V_{IH}$ | | ± 10 | μA |
| V_{IL} | Input low level | | -0.6 | 0.8 | V |
| V_{IH} | Input high level | | 2.0 | $V_{CC} + 0.1$ | V |
| V_{OL} | Output low voltage | $I_{OL} = 2.1\text{mA}$ | | 0.4 | V |
| V_{OH} | Output high voltage | $I_{OH} = -400\mu\text{A}$ | 2.4 | | V |
| I_{CC2} | V_{CC} supply current (program and verify) | | | 50 | mA |
| I_{PP2} | V_{PP} supply current | $\overline{CE} = \overline{PGM} = V_{IL}$ | | 30 | mA |
| V_{ID} | A9 product identification voltage | | 11.5 | 12.5 | V |

Table 5-7. AC programming characteristics

 $T_A = 25 \pm 5^\circ\text{C}$, $V_{CC} = 6.5 \pm 0.25\text{V}$, $V_{PP} = 13.0 \pm 0.25\text{V}$

| Symbol | Parameter | Test conditions ⁽¹⁾ | Limits | | Units |
|-----------|---|--|--------|-----|---------------|
| | | | Min | Max | |
| t_{AS} | Address setup time | Input rise and fall times (10% to 90%) 20ns | 2 | | μs |
| t_{CES} | \overline{CE} setup time | | 2 | | μs |
| t_{OES} | \overline{OE} setup time | | 2 | | μs |
| t_{DS} | Data setup time | | 2 | | μs |
| t_{AH} | Address hold time | Input pulse levels 0.45V to 2.4V | 0 | | μs |
| t_{DH} | Data hold time | | 2 | | μs |
| t_{DFP} | \overline{OE} high to output float delay ⁽²⁾ | Input timing reference level | 0 | 130 | ns |
| t_{VPS} | V_{PP} setup time | 0.8V to 2.0V | 2 | | μs |
| t_{VCS} | V_{CC} setup time | | 2 | | μs |
| t_{PW} | \overline{PGM} program pulse width ⁽³⁾ | Output timing reference level 0.8V to 2.0V | 95 | 105 | μs |
| t_{OE} | Data valid from \overline{OE} | | | 150 | ns |
| t_{PRT} | V_{PP} pulse rise time during programming | | 50 | | ns |

- Notes:
- V_{CC} must be applied simultaneously with or before V_{PP} and removed simultaneously with or after V_{PP} .
 - This parameter is only sampled, and is not 100% tested. Output float is defined as the point where data is no longer driven. See timing diagram.
 - Program pulse width tolerance is $100\mu\text{sec} \pm 5\%$.

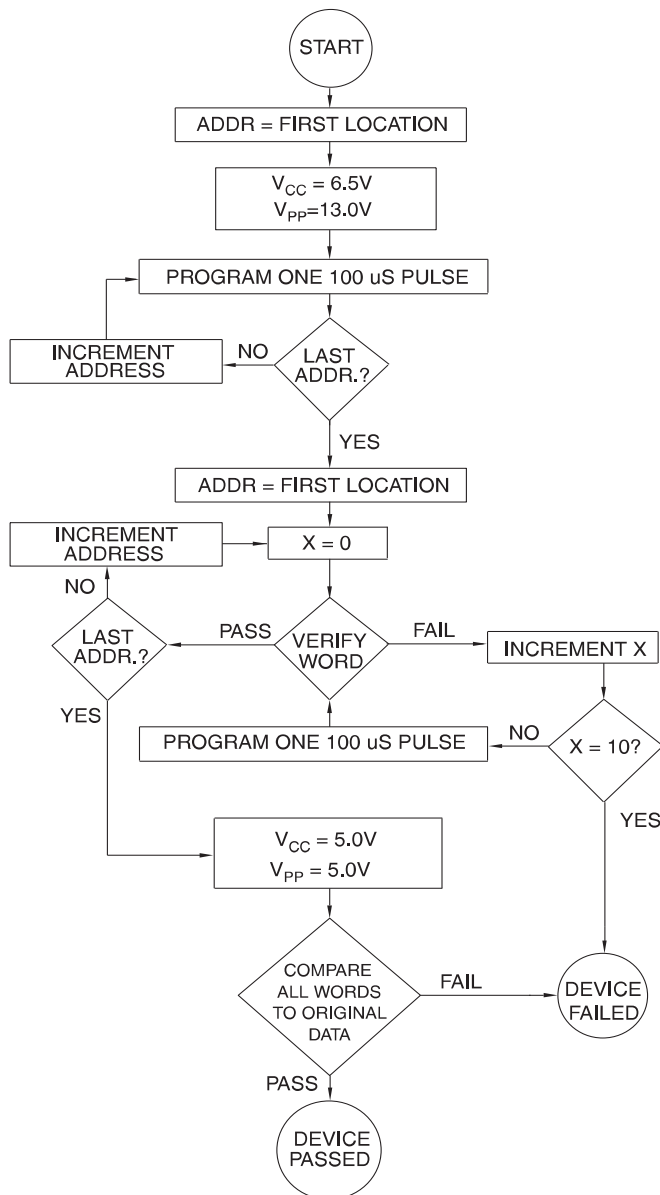
Table 5-8. The Atmel AT27C1024 integrated product identification code

| Codes | Pins | | | | | | | | | | Hex data |
|--------------|------|--------|----|----|----|----|----|----|----|----|----------|
| | A0 | O15-O8 | O7 | O6 | O5 | O4 | O3 | O2 | O1 | O0 | |
| Manufacturer | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 001E |
| Device type | 1 | 0 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 00F1 |

6. Rapid programming algorithm

A $100\mu\text{s}$ $\overline{\text{PGM}}$ pulse width is used to program. The address is set to the first location. V_{CC} is raised to 6.5V and V_{PP} is raised to 13.0V. Each address is first programmed with one $100\mu\text{s}$ $\overline{\text{PGM}}$ pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a word fails to pass verification, up to 10 successive $100\mu\text{s}$ pulses are applied with a verification after each pulse. If the word fails to verify after 10 pulses have been applied, the part is considered failed. After the word verifies properly, the next address is selected until all have been checked. V_{PP} is then lowered to 5.0V and V_{CC} to 5.0V. All words are read again and compared with the original data to determine if the device passes or fails.

Figure 6-1. Rapid programming algorithm



7. Ordering information

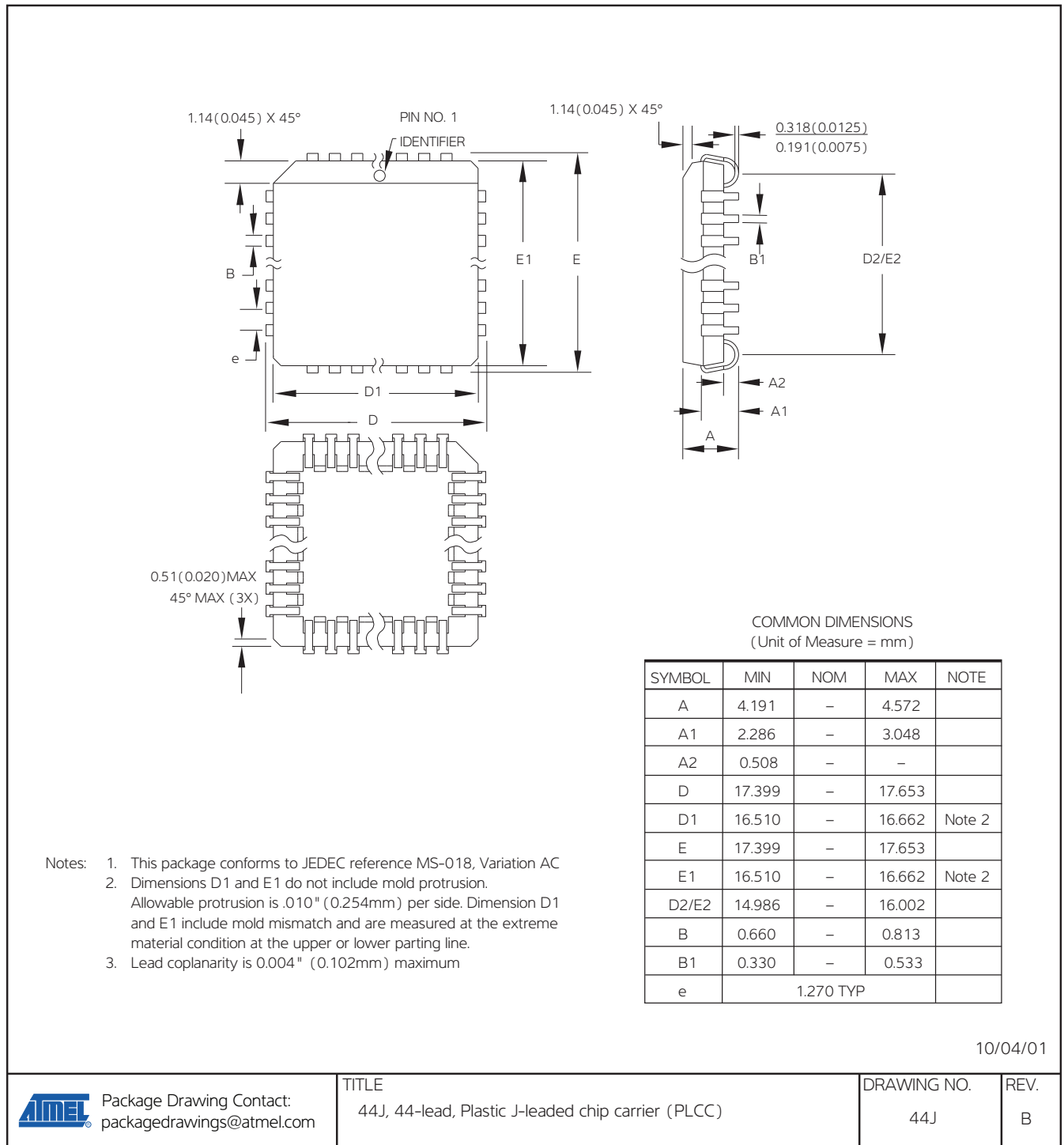
Green Package (Pb/halide-free)

| t_{ACC} (ns) | I_{CC} (mA) | | Atmel ordering code | Package | Lead finish | Operation range |
|-------------------|---------------|---------|----------------------------------|-------------|------------------------|-------------------------------|
| | Active | Standby | | | | |
| 45 | 30 | 0.1 | AT27C1024-45JU AT27C1024-45PU | 44J 40P6 | Matte tin Matte tin | Industrial (-40°C to 85°C) |
| 70 | 30 | 0.1 | AT27C1024-70JU AT27C1024-70PU | 44J 40P6 | Matte tin Matte tin | Industrial (-40°C to 85°C) |

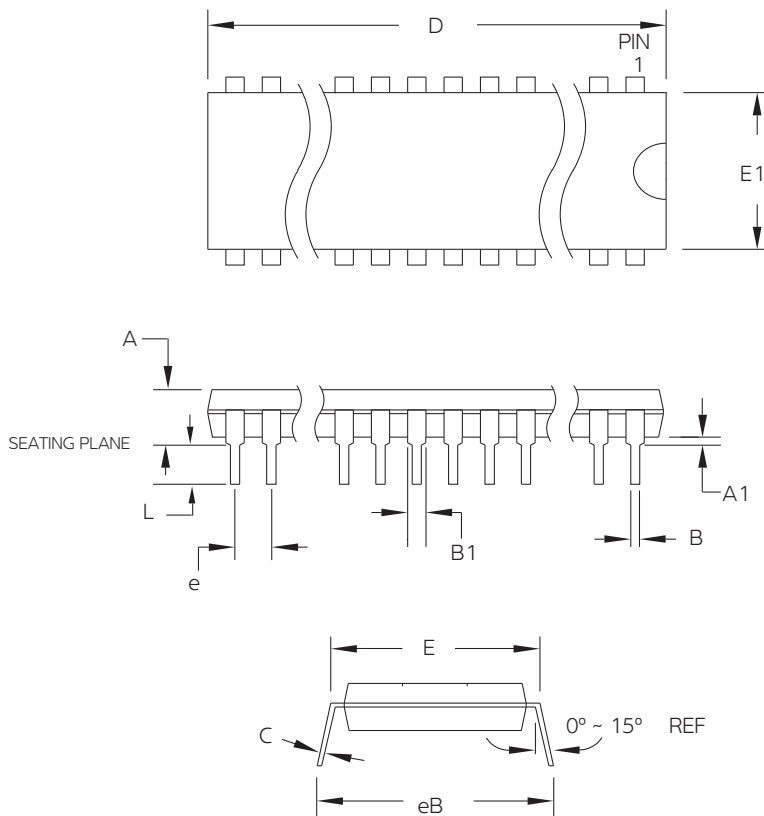
| Package type | |
|--------------|---|
| 44J | 44-lead, plastic, J-leaded chip carrier (PLCC) |
| 40P6 | 40-lead, 0.600" wide, plastic, dual inline package (PDIP) |

8. Packaging information

44J – PLCC



40P6 – PDIP



- Notes:
1. This package conforms to JEDEC reference MS-011, Variation AC.
 2. Dimensions D and $E1$ do not include mold Flash or Protrusion.
Mold Flash or Protrusion shall not exceed 0.25mm (0.010").

COMMON DIMENSIONS
(Unit of Measure = mm)

| SYMBOL | MIN | NOM | MAX | NOTE |
|--------|-----------|-----|--------|--------|
| A | – | – | 4.826 | |
| A1 | 0.381 | – | – | |
| D | 52.070 | – | 52.578 | Note 2 |
| E | 15.240 | – | 15.875 | |
| E1 | 13.462 | – | 13.970 | Note 2 |
| B | 0.356 | – | 0.559 | |
| B1 | 1.041 | – | 1.651 | |
| L | 3.048 | – | 3.556 | |
| C | 0.203 | – | 0.381 | |
| eB | 15.494 | – | 17.526 | |
| e | 2.540 TYP | | | |

09/28/01



Package Drawing Contact:
packagedrawings@atmel.com

TITLE

40P6, 40-lead (0.600"/15.24mm Wide) Plastic Dual
Inline Package (PDIP)

DRAWING NO.

40P6

REV.

B

9. Revision history

| Doc. Rev. | Date | Comments |
|-----------|---------|--|
| 0019N | 04/2011 | Remove VSOP package Add lead finish to ordering information |
| 0019M | 12/2007 | |

**Atmel Corporation**

2325 Orchard Parkway
San Jose, CA 95131
USA

Tel: (+1) (408) 441-0311

Fax: (+1) (408) 487-2600

www.atmel.com

Atmel Asia Limited

Unit 01-5 & 16, 19F
BEA Tower, Millennium City 5
418 Kwun Tong Road
Kwun Tong, Kowloon
HONG KONG

Tel: (+852) 2245-6100

Fax: (+852) 2722-1369

Atmel Munich GmbH

Business Campus
Parkring 4
D-85748 Garching b. Munich
GERMANY

Tel: (+49) 89-31970-0

Fax: (+49) 89-3194621

Atmel Japan

9F, Tonetsu Shinkawa Bldg.
1-24-8 Shinkawa
Chuo-ku, Tokyo 104-0033
JAPAN

Tel: (+81) (3) 3523-3551

Fax: (+81) (3) 3523-7581

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